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16.07 Dynamics Fall 2008 Version 2.0

Lecture L25 - 3D Rigid Body Kinematics

In this lecture, we consider the motion of a 3D rigid body. We shall see that in the general three-dimensional case, the angular velocity of the body can change in magnitude as well as in direction, and, as a consequence,

3D Rigid Body Kinematics - MIT OpenCourseWare

In lecture L12, we derived three basic relationships embodying Kepler's laws: ... Note that the origin (zero potential) for the gravitational potential is taken to be at infinity. Therefore, for finite values of r , the potential is ... J.L. Meriam and

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L.G. Kraige, Engineering Mechanics,
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Lecture L16 - Central Force Motion - MIT OpenCourseWare

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tion. Note that in order to understand the rest of this paper, the reader need not understand the derivation of these equations. The derivation is presented for completeness and can be found in J. L. Meriman. As a rope bends over a small segment of a drum, the tension in a rope will increase from T to $T+dT$ in an angle $d\theta$.

The Mechanics of Friction in Rope Rescue

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